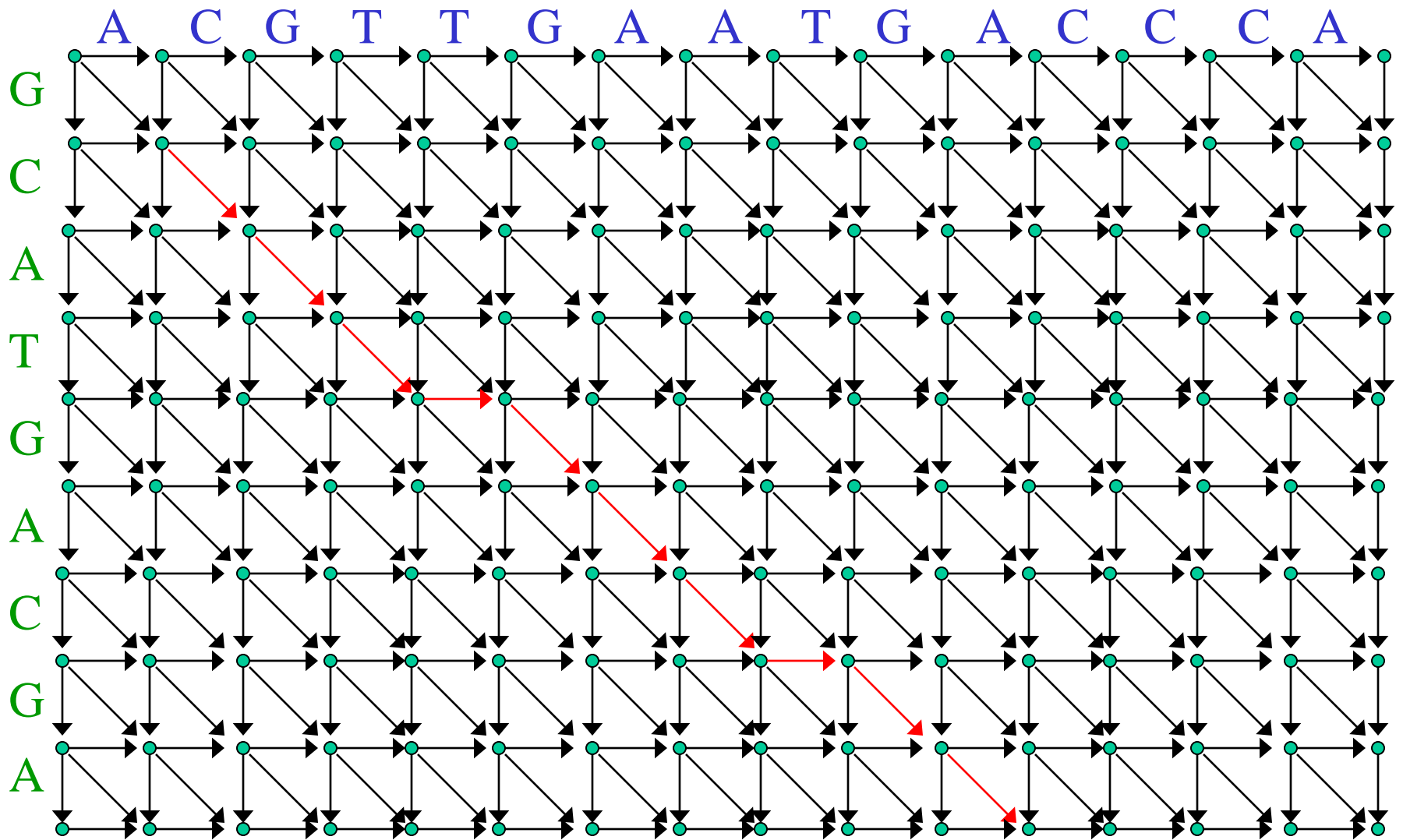


Lecture 10

- Reducing memory
 - Linear space algorithms
- Finding internal repeats
- Genome alignment



Above **path** corresponds to following alignment (w/ lower case letters considered unaligned):

aCGTTGAATGAccca
gCAT-GAC-GA

- To reconstruct best path, need “**traceback**” pointer to immediate predecessor of v in best path:

$$T(v) = \begin{cases} v & w(v) = 0 \\ \arg \max_{u \in \text{parents}(v)} (w(u) + w((u,v))) & w(v) \neq 0 \end{cases}$$

- in preceding graph, $T(v)$ is the *parent* on **red edge** coming into v
 - if more than one such edge, pick one at random;
 - if no such edge, $T(v) = v$
- Sometimes useful to record **beginning** of best path:

$$B(v) = \begin{cases} v & w(v) = 0 \\ B(T(v)) & w(v) \neq 0 \end{cases}$$

Linear Space Algorithm for Full Alignment Reconstruction

- Space complexity 10^{12} (for pairwise genome-scale alignments) is unacceptable.
 - Following algorithm (based on principle of *divide-and-conquer*) trades
 - ~ 2 -fold increase in time
 - Maybe! Will save on cache misses ...
- for
- reducing space requirement to $O(\min(M,N))$:
- [rarely used in practice however – instead one typically tries to work with “well-anchored” pieces smaller than 1 Mb]

“Forward-backward” method to find where highest-scoring path crosses **midline** of edit graph:

- do dynamic programming scans
 - from left bdry to midline,
 - from right bdry to midline.

• Then $\max_{v \text{ on midline}} w(v) + w'(v)$ is highest weight of any path through midline, and

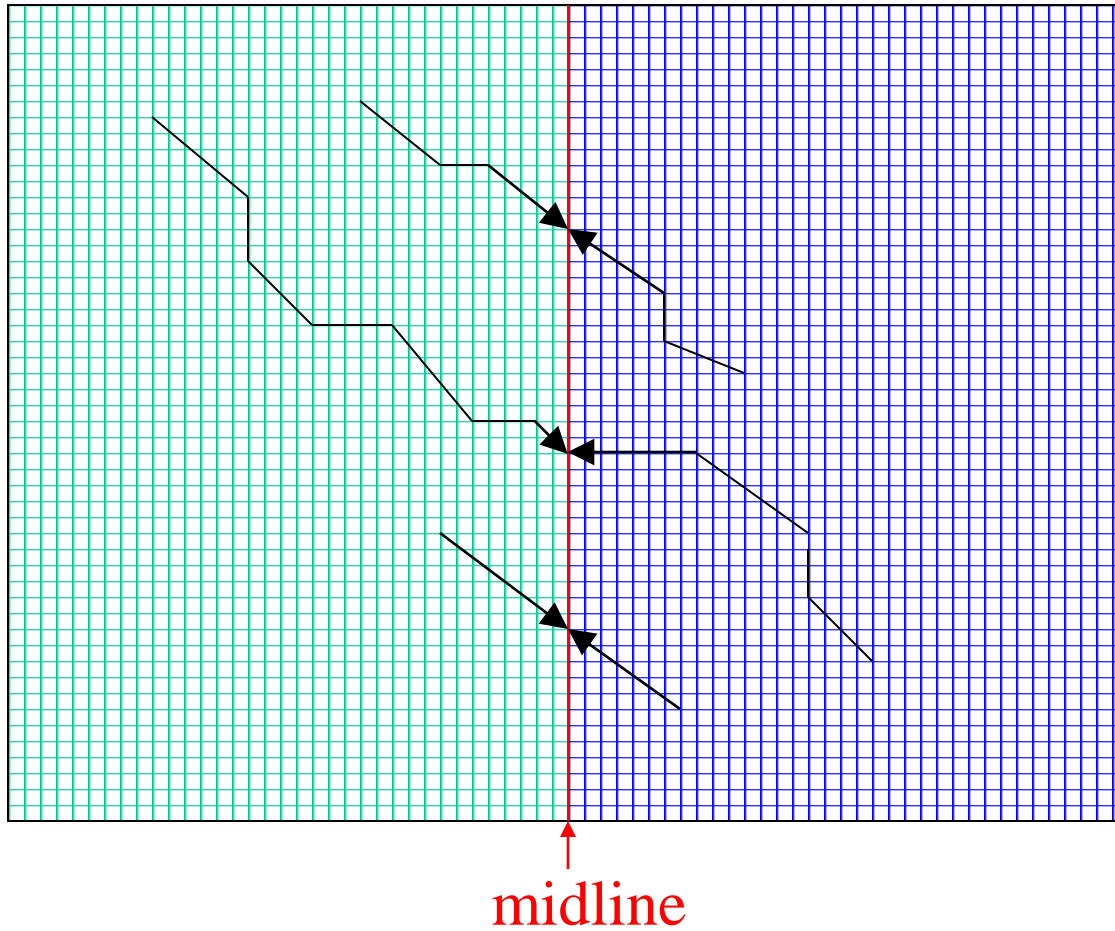
$$M(v) = \arg \max_{v \text{ on midline}} w(v) + w'(v)$$

is vertex where intersects midline.

- Iterate on subgraphs.

→
scan from left

←
scan from right



Inverted WDAGs

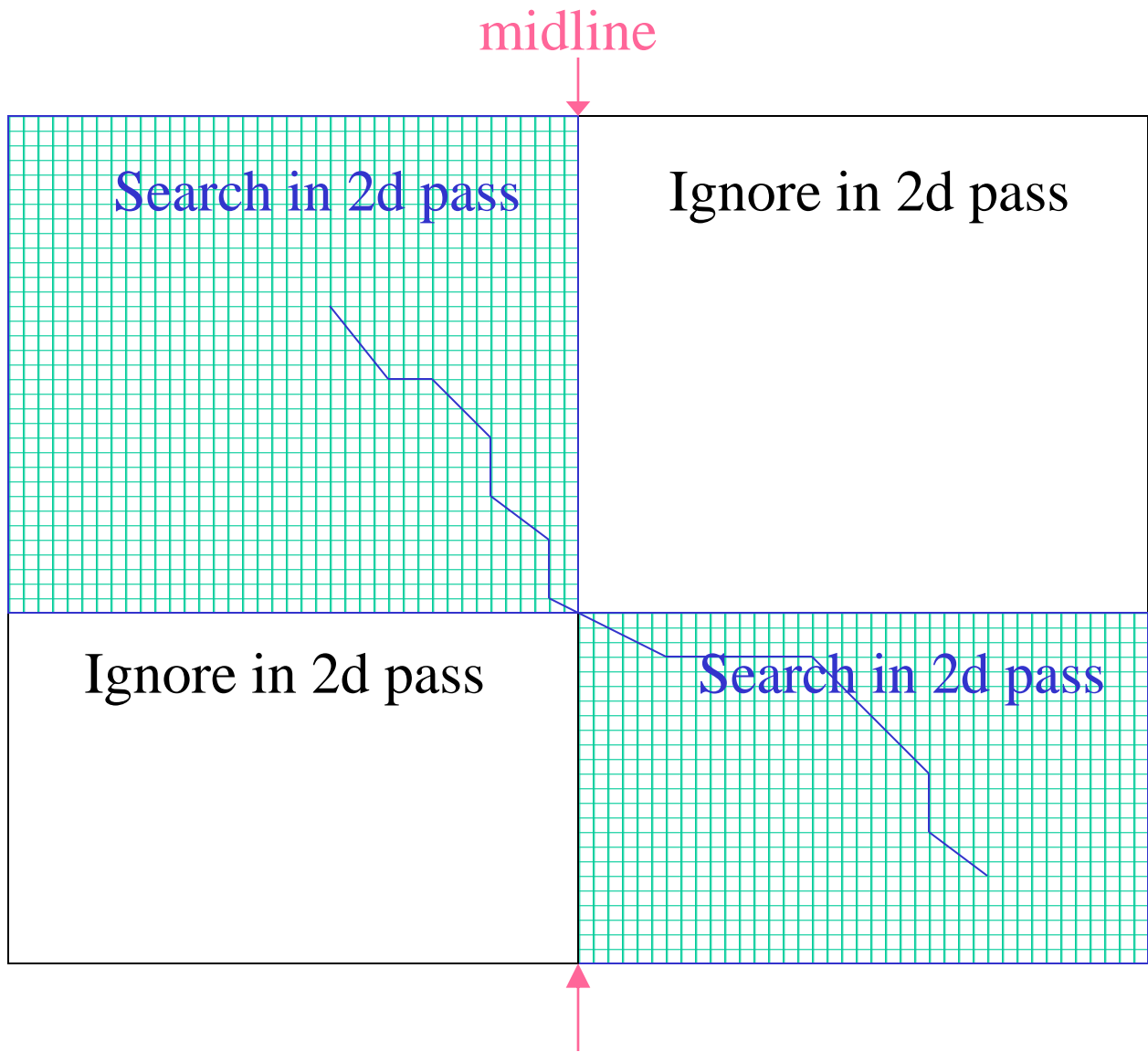
- Can “invert” any WDAG: create graph with
 - same vertices & edge weights
 - direction of each edge reversed
- inverted WDAG has same paths & path weights, but in reverse order
- inverting does not necessarily “invert” depth structure

Scanning WDAG in Both Directions

- Order vertices (v_1, v_2, \dots, v_n) with parents preceding children.
 - Find $w(v)$, highest weight of path (“from left”) ending at v .
- Reverse order $(v_n, v_{n-1}, \dots, v_1)$ has parents before children in *inverted* graph
 - Find $w'(v)$, highest weight of path (“from right”) ending at v .
- Then
 - (joining path from left ending at v , to reverse of path from right ending at v),
see that $w(v) + w'(v)$ is highest weight of any path going *through* v .
- This construction will also arise later, with HMMs.

Linear space algorithm (cont'd)

- Now do 2nd pass, *only scanning part of graph where highest weight path must lie*:
 - bounded by midline, and line through $M(v)$ (or just midline, if doesn't cross it):
 - only $\frac{1}{2}$ as many edges and vertices as in 1st pass
 - Now store location where crosses midline *of each subgraph*.



Iterate!

- In 3rd pass, need
 - 1/2 # edges and vertices in 2nd pass,
 - i.e. only 1/4 # in 1st pass.
- etc. until down to subgraphs consisting of single row or column
- can piece together full path from midline intersections in each pass
- Total effective search space: $1 + 1/2 + 1/4 + \dots = 2$,
i.e. only *twice* the initial search.

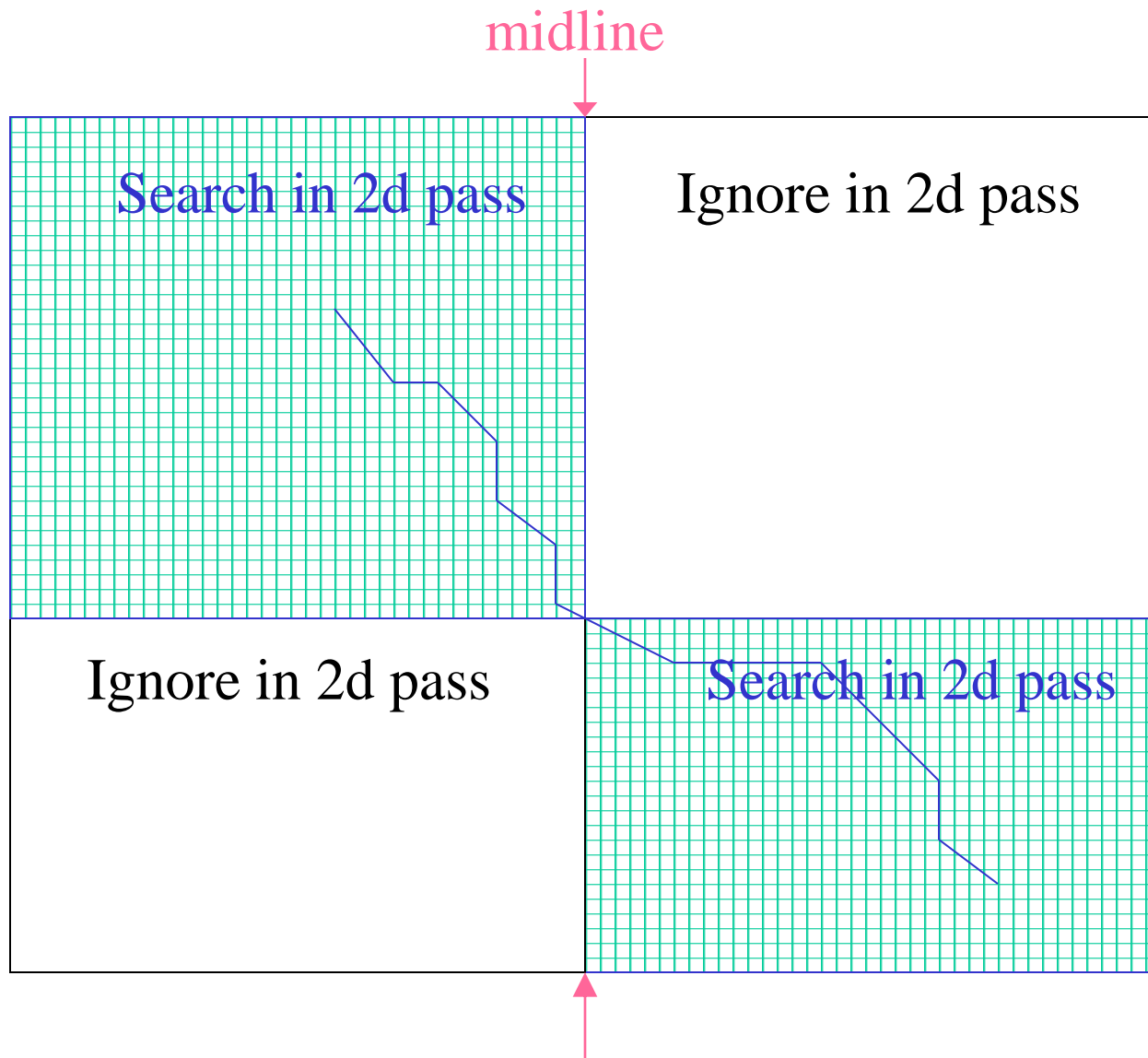
Alternate method – not using inverted WDAG

- Idea: in first pass, record where highest-weight path ending at v crosses *midline* of graph:

$$M(v) = \begin{cases} 0 & v \text{ lies to left of midline, or } v = T(v) \\ v & v \text{ lies on midline} \\ M(T(v)) & v \text{ lies to right of midline} \end{cases}$$

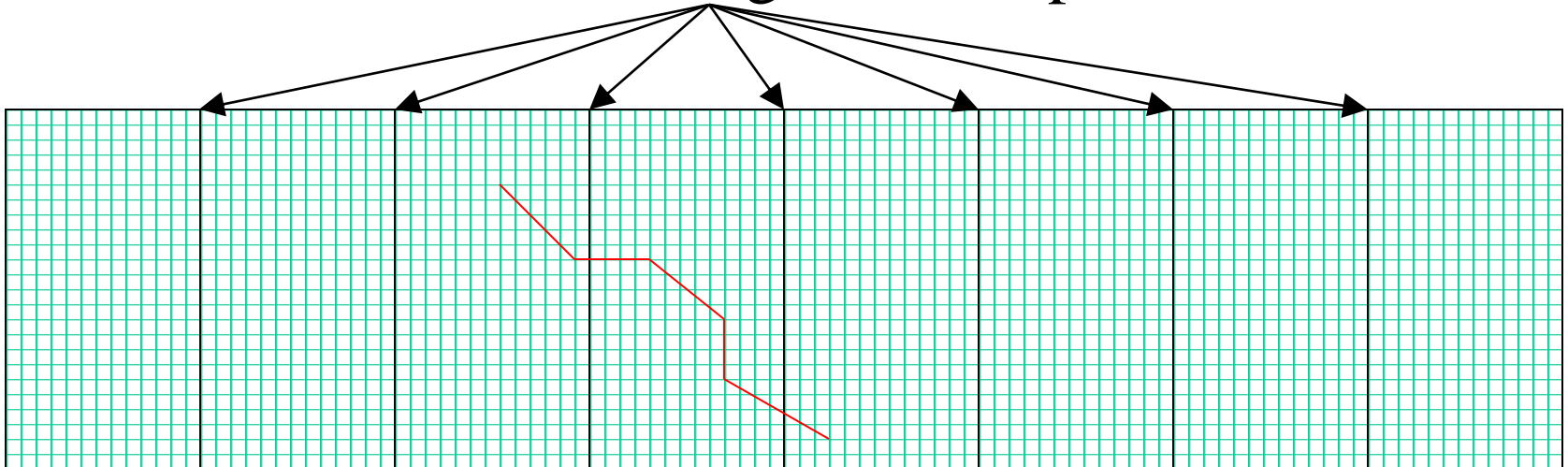
where $T(v)$ is parent of v through which best path ending at v passes.

- Note that (as when recording beginning of path, $B(v)$)
 - only need retain $M(v)$ until all children of v processed (or for current best v);
 - so requires $O(\min(M,N))$ space, for appropriate processing order.
- In subsequent pass, only scan part of graph where highest weight path must lie
 - bounded by midline, and line through $M(v)$ (or just midline, if doesn't cross it):



Linear Space – Variant Algorithms

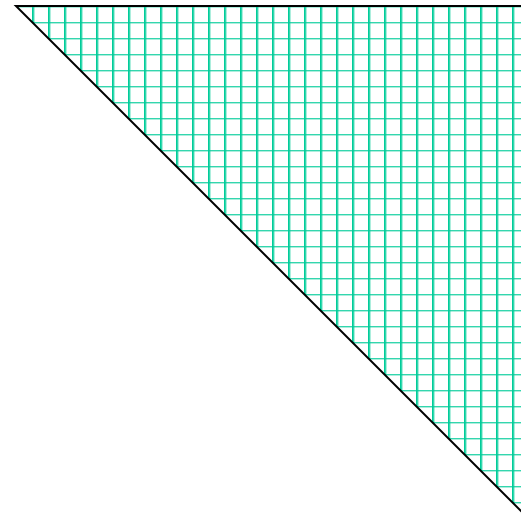
- Can store more intermediate points (e.g. have n lines, record where crosses each one).
 - increases required space, but
 - decreases time ($1/n$ instead of $1/2$) for subsequent pass.
- Choose n to minimize time, given the space available.



Finding (imperfect) internal repeats

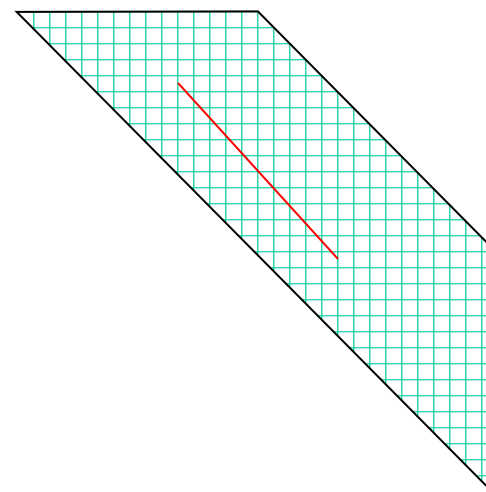
- Search edit graph of *sequence against itself*
 - i.e. the same sequence labels columns and rows
- above (& not including) the main diagonal:*
 - if include main diagonal, best path will be identity match to self
 - complexity = $O(N^2)$ where N = sequence length.

Graph for finding imperfect
internal repeats:



- Find *short tandem repeats* (e.g. microsatellites, minisatellites):
 - scan a *band* just above main diagonal.
 - Complexity = $O(kN)$ where k is width of the band.
 - Manageable even for large N , if k small.

Graph for finding short tandem repeats:



ACACACACACACACAC
ACACACACACACACAC

Genome alignment

- Challenges:
 - Size
 - Repeated sequence
 - Duplications
 - Transposable elements
 - Processed pseudogenes
 - Other segmental changes
 - Deletions
 - Inversions, translocations
 - Mutation rate variation
- Segmental changes don't conform to edit graph framework!

Strategy

- Find (many!) word-nucleated local alignments
- Word size w : sensitivity vs specificity
 - Example: human (~3 Gb) vs mouse (~2.5 Gb)
 - ~70% identity in homologous regions
 - For each human word, expect $5 \times 10^9 / 4^w$ chance occurrences in mouse (+ rev complement)
 - Total matches: $15 \times 10^{18} / 4^w$
 - Want w *large enough* for this to be manageable
 - Prob that the *homologous* word matches: $.7^w$
 - once every $(1 / .7)^w = 1.43^w$ bp
 - Want w *small enough* to ensure ≥ 1 match within homologous regions
 - $w = 15$: $\sim 15 \times 10^9$ matches; 1 per 214 homologous bp

- Avoid high-frequency words
- Avoid nucleating in known repeats & duplications
 - But extend into them!
- Use appropriate score matrix & gap penalties!
 - Otherwise, get junk alignments or portions thereof

- Finally, identify *chains of compatible* local alignments
 - Ideally, catalogue the segmental changes that have occurred (duplications, transposable element insertions etc)